

## 2.1 Model definition

$\mathbf{z}(\mathbf{x}, t) = \mathbf{I} - \mathbf{z}(\mathbf{x}, t) + \mathbf{z}(\mathbf{x}, t) H(\mathbf{z}(\mathbf{x}, t) - \theta)$

$$\mathbf{z}(\mathbf{x}, t) = \mathbf{I} - \frac{\mathbf{z}(\mathbf{x}, t) + \mathbf{z}(\mathbf{x}, t) H(\mathbf{z}(\mathbf{x}, t) - \theta)}{\epsilon \cdot \|\mathbf{z}(\mathbf{x}, t)\|} Z(\mathbf{x}, t). \quad (.1)$$

$\mathbf{z}(\mathbf{x}, t) = \mathbf{I} - \frac{\mathbf{z}(\mathbf{x}, t) + \mathbf{z}(\mathbf{x}, t) H(\mathbf{z}(\mathbf{x}, t) - \theta)}{\epsilon \cdot \|\mathbf{z}(\mathbf{x}, t)\|} Z(\mathbf{x}, t)$

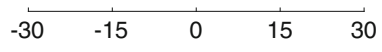
$(L, t) = (-L, t)$

$H(-\theta) =$

$$Z(x, y) = \frac{\epsilon C(0) \int_{\mathbb{R}^2} [(\cdot, \cdot)] / \sqrt{\epsilon} \, dx \, dy}{\epsilon} \quad (1.5)$$

## 2.2 Single bump solutions

$$\begin{aligned} & (Z = 0) \quad (1) \\ & (0) \quad (2) \\ & (1) \quad (3) \\ & (1) \quad (4) \end{aligned}$$



$$\begin{aligned}
 & \text{for } j = 1, \dots, J, \text{ we have } \dots \text{ (1)} \\
 & \dots \text{ (2)} \\
 & \dots W(\dots) \\
 & \dots \\
 & \dots (j) - \dots = W(\dots - 1), \\
 & \dots \\
 & \dots \\
 & \dots j) = \frac{(-1)^j}{\bar{\alpha}} [-\theta + W(\dots - 1)] \\
 & \dots + \overline{\epsilon \cdot \theta} \cdot Z(j), \dots \text{ (1)}
 \end{aligned}$$

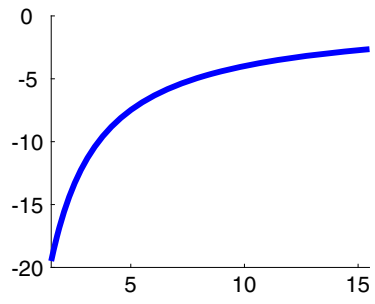
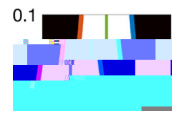
$$\begin{aligned}
 & \text{for } j = 1, \dots, J, \text{ we have } \dots \text{ (1)} \\
 & \dots (Z = 0), \dots \\
 & \dots \\
 & \dots j) = \frac{(-1)^j}{\bar{\alpha}} (-\theta + W(\dots - 1)) \text{ (2)} \\
 & \dots j = 1, \dots, J, \text{ we have } \dots (1, \dots), \dots W(\dots - 1) = \theta
 \end{aligned}$$

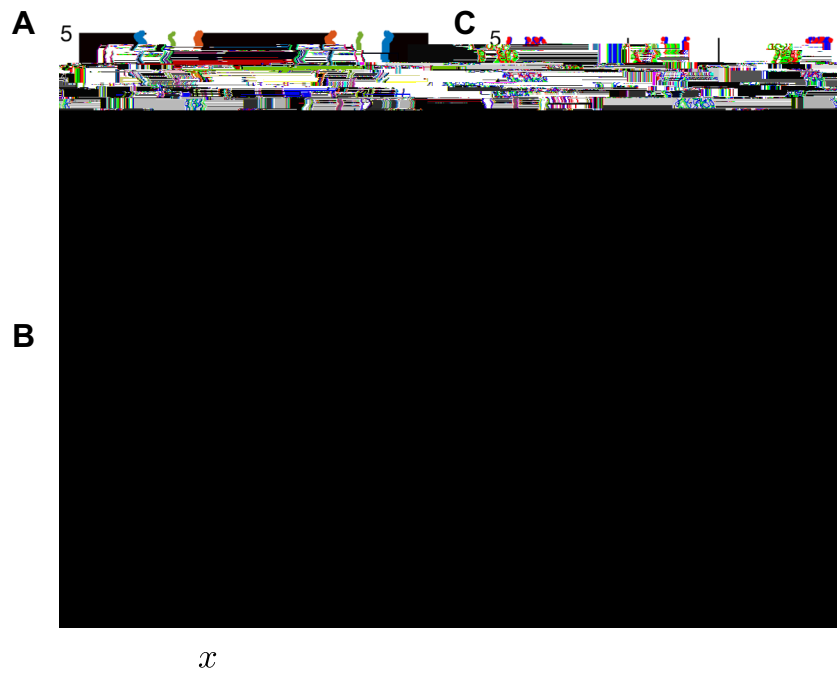


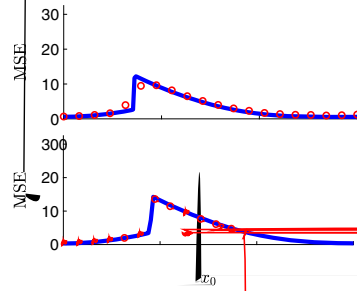
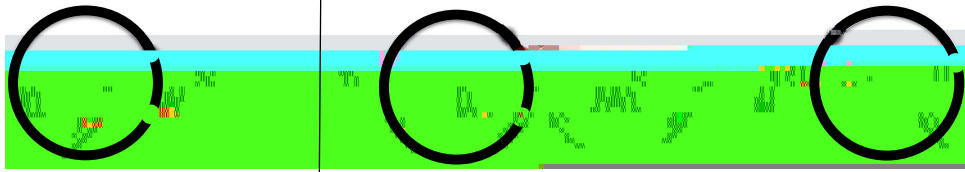




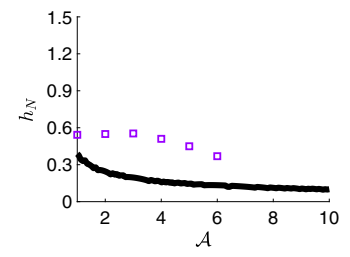








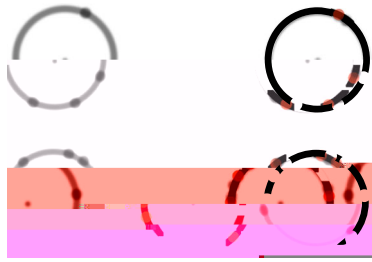


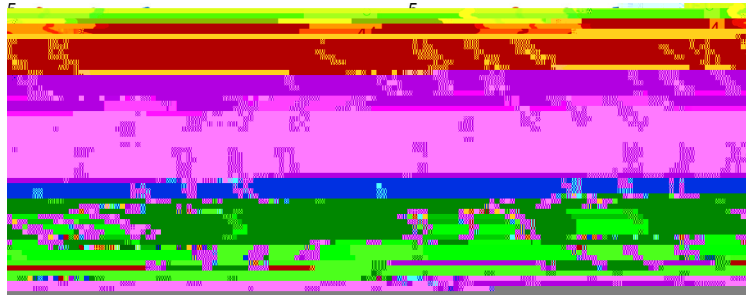


$$\hat{h}_N \in [0, d_N/2)$$

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$1, \dots, M)$ .  $\dots$

$$A(0) = [-b_0, -a_0] \times \{j\} \cup [a_0, b_0] \times \{k\},$$

$\dots$   $(W_{jk}(\cdot) - W_{kj}(\cdot), j, k)$ .  
 $\dots$  (5.5)

$$a_1(\cdot) = \frac{1}{\bar{\alpha}} \theta - W(b_1 - a_1) - W_{jk}(b - a_1) + W_{jk}(a - a_1), \quad (5.6)$$

$$b_1(\cdot) = -\frac{1}{\bar{\alpha}} \theta - W(b_1 - a_1) - W_{jk}(b - b_1) + W_{jk}(a - b_1), \quad (5.7)$$

$$a(\cdot) = \frac{1}{\bar{\alpha}} \theta - W(b - a) - W_{kj}$$





## Acknowledgements

140–40). (2015).

## Compliance with Ethical Standards

### Conflict of interests

## References

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