Predicting Criticality and Dynamic Range in Complex Networks: Effects of Topology

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... dynamic range ...

e r res s se F a res s q a a e b a r. I a r a, $\lim_{□\to 0} F = 0$ □ < 1 a $\lim_{□\to 0} F > 0$ □ > 1. I a , e a r a e e e r a r b a e a □ = 1 T e a a e er □ s e e R s. [2,4] a a ae r a e b a r a , r e e e a $□ = \frac{1}{N}\sum_{i;j} A_{ij} = \langle$

[illegible] ∈ [2.0; 6.0], [illegible] 5) [illegible] $\langle d \rangle = 1$, [illegible] [0.7; 1.3]; [illegible] 6) [illegible], $A_{ij} = $ [illegible]$/d^{out}$.

We [illegible] ($A_{ij} \in \{0; 1\}$) [illegible] 0 [illegible]

[illegible] Refs. [2,7] [illegible] [7]. [illegible] $\in [2.0, 6.0]$, [illegible] $= 1$ [illegible] Eq. (9) [illegible] Fig. 3.

[illegible] $= 1$. [illegible] More[illegible] [illegible] (see [19] [illegible]) [illegible] [4] [illegible]

[illegible] (1) [illegible] ≈ 1, [illegible] (2) [illegible]

We [illegible] E[illegible] O[illegible] D[illegible] Pe[illegible]